

# ***VAN'S AIRCRAFT***

**TOTAL PERFORMANCE**

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## **REVISION DESCRIPTION:**

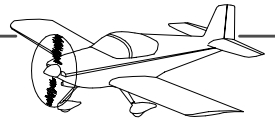
**Page 44-06 REV 1:** Added "WARNING: ...".

**Page 44A-04 REV 3:** Add "(WITH FLAPS UP AND WITH FLAPS DOWN)" to the WARNING.

**Page 44B-06 REV 1:** Add "(WITH FLAPS UP AND WITH FLAPS DOWN)" to the WARNING.

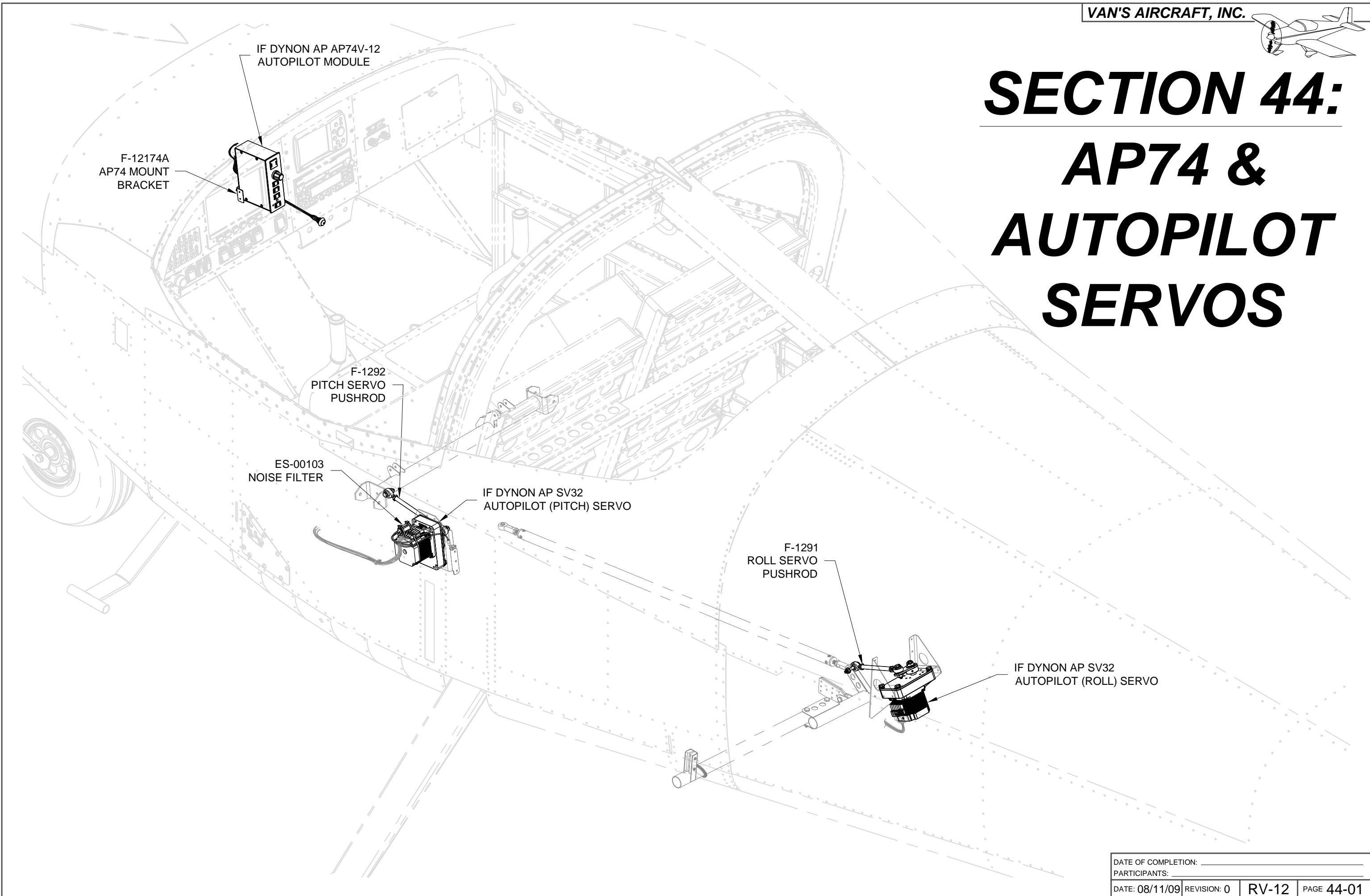
**Page 44B-07 REV 2:** Show additional cut lines for GMC 307 in Figure 2.

Add "(GMC 305)" after hardware callouts in Figure 2.



# SECTION 44:

## AP74 & AUTOPILOT SERVOS

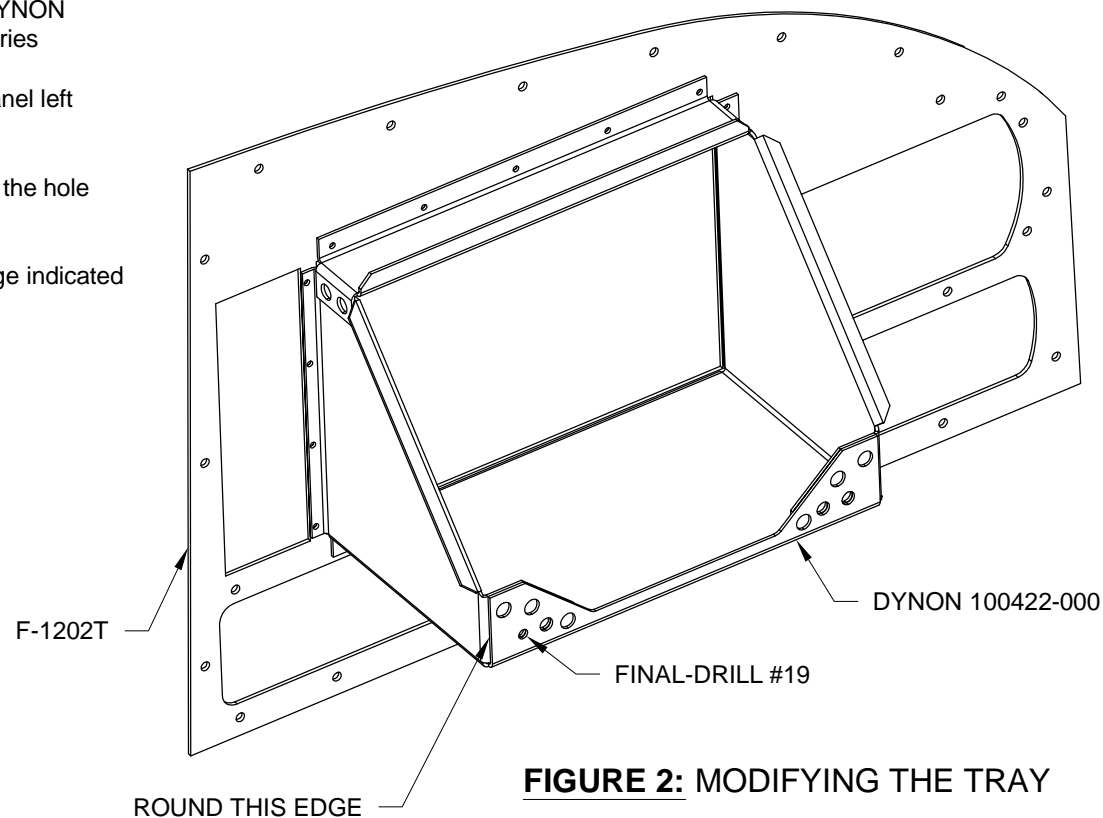


**Step 1:** Remove the IF DYNON DEK 180-12 Dynon EFIS/EMS from the DYNON 100422-000 D-100 Series Mounting Tray attached to the F-1202T Inst Panel Left D-180. Disconnect the Static and Pitot Lines and WH-RV12-DYNON Dynon D-180 Harness from the back of the Dynon EFIS/EMS. Remove the inst panel left D-180 and D-100 series mounting tray from the aircraft. See Section 29 and Section 42 for reference. Remove the AV CONTROL BOARD 12 Switch Fuse Connector PCB.

**Step 2:** Use two sets of 6-32 screws and nuts to align the F-12174B AP74 Drill Template to the F-1202T Inst Panel Left D-180. Match-Drill #40 the holes of the AP74 drill template into the inst panel left D-180. Remove the AP74 drill template and remove all the material up to the outside edges of the holes. Square the corner holes. Note that this will also remove a significant portion of the flange of the DYNON 100422-000 D-100 Series Mounting Tray attached to the inst panel left D-180. See Figure 1.

**Step 3:** Final-Drill #19 the hole indicated in Figure 2.

**Step 4:** Round the edge indicated in Figure 2 with a file.



**FIGURE 1: MAKING THE AP74 CUTOUT**

**FIGURE 2: MODIFYING THE TRAY**

**Step 5:** Use an 8-32 screw to align the F-12174A AP74 Mount Bracket as shown in Figure 3. Double check that the AP74 mount bracket pushes up tight against the back and side of the DYNON 100422-000 D-100 Series Mounting Tray as shown in Figure 3. If required repeat Step 4.

**Step 6:** Match-Drill #40 both holes in the F-12174A AP74 Mount Bracket into the side of the DYNON 100422-000 D-100 Series Mounting Tray as shown in Figure 3. Remove the AP74 mount bracket.

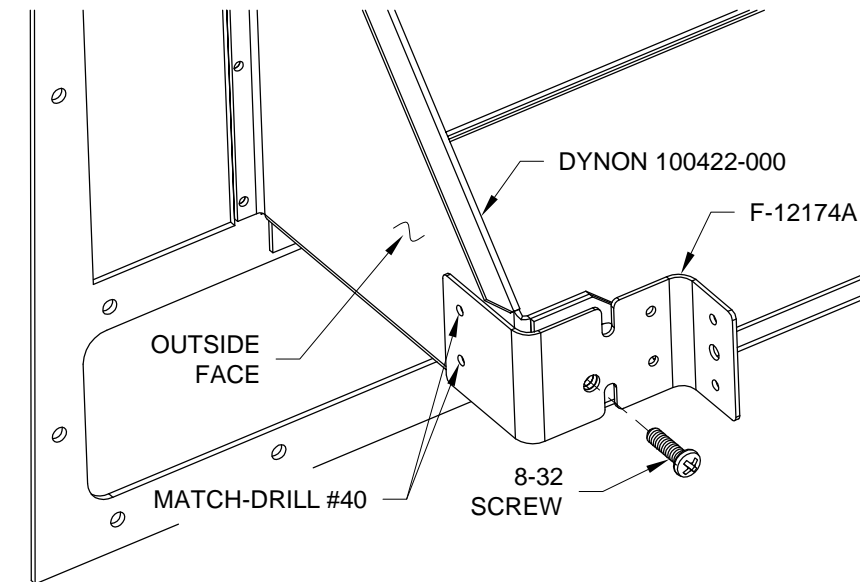
**Step 7:** Dimple the two holes drilled in Step 6 in the DYNON 100422-000 D-100 Series Mounting Tray, flush on the **inside** face.

**Step 8:** Remove the template portion of the F-12174A AP74 Mount Bracket as shown in Figure 4.

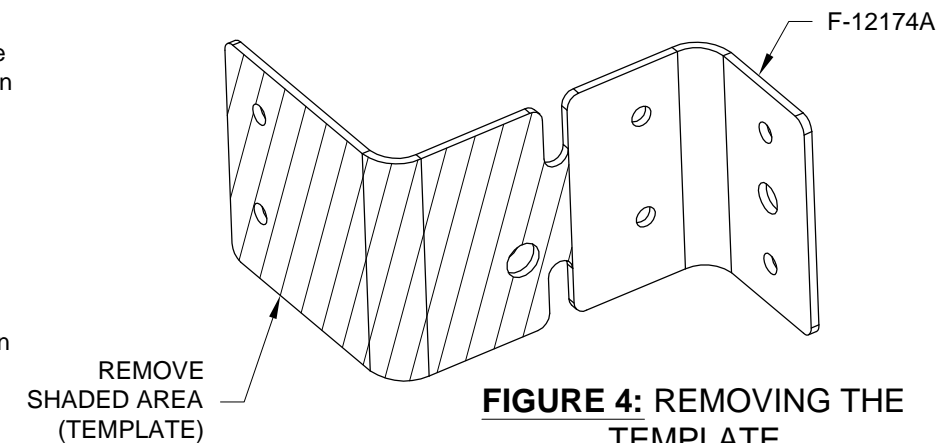
**Step 9:** Dimple the F-12174A AP74 Mount Brackets two nutplate attach holes and the two holes that will attach the AP74 mount bracket to the DYNON 100422-000 D-100 Series Mounting Tray. See Figure 5 to determine correct dimple direction. Dimple the attach holes in the nutplate called out in Figure 5.

**Step 10:** Rivet the nutplate called out in Figure 5 to the F-12174A AP74 Mount Bracket.

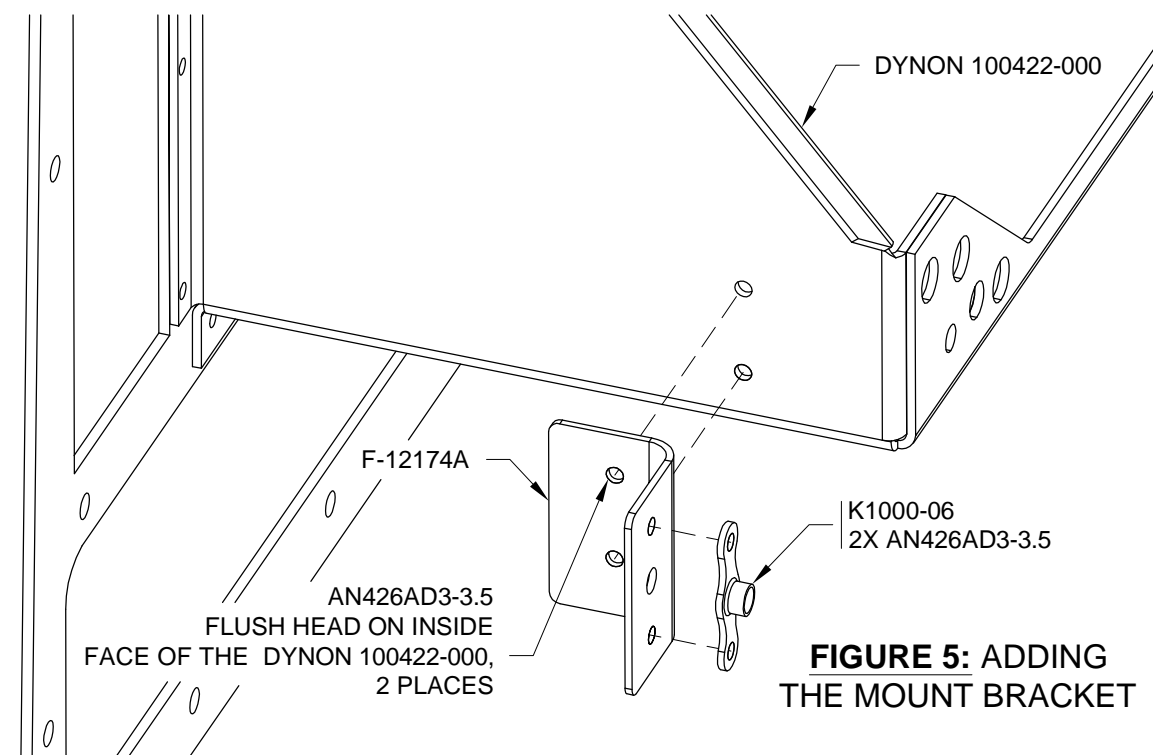
**Step 11:** Rivet the F-12174A AP74 Mount Bracket to the DYNON 100422-000 D-100 Series Mounting Tray as shown in Figure 5.



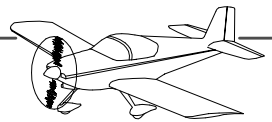
**FIGURE 3: MATCH-DRILLING THE TRAY**



**FIGURE 4: REMOVING THE TEMPLATE**



**FIGURE 5: ADDING THE MOUNT BRACKET**



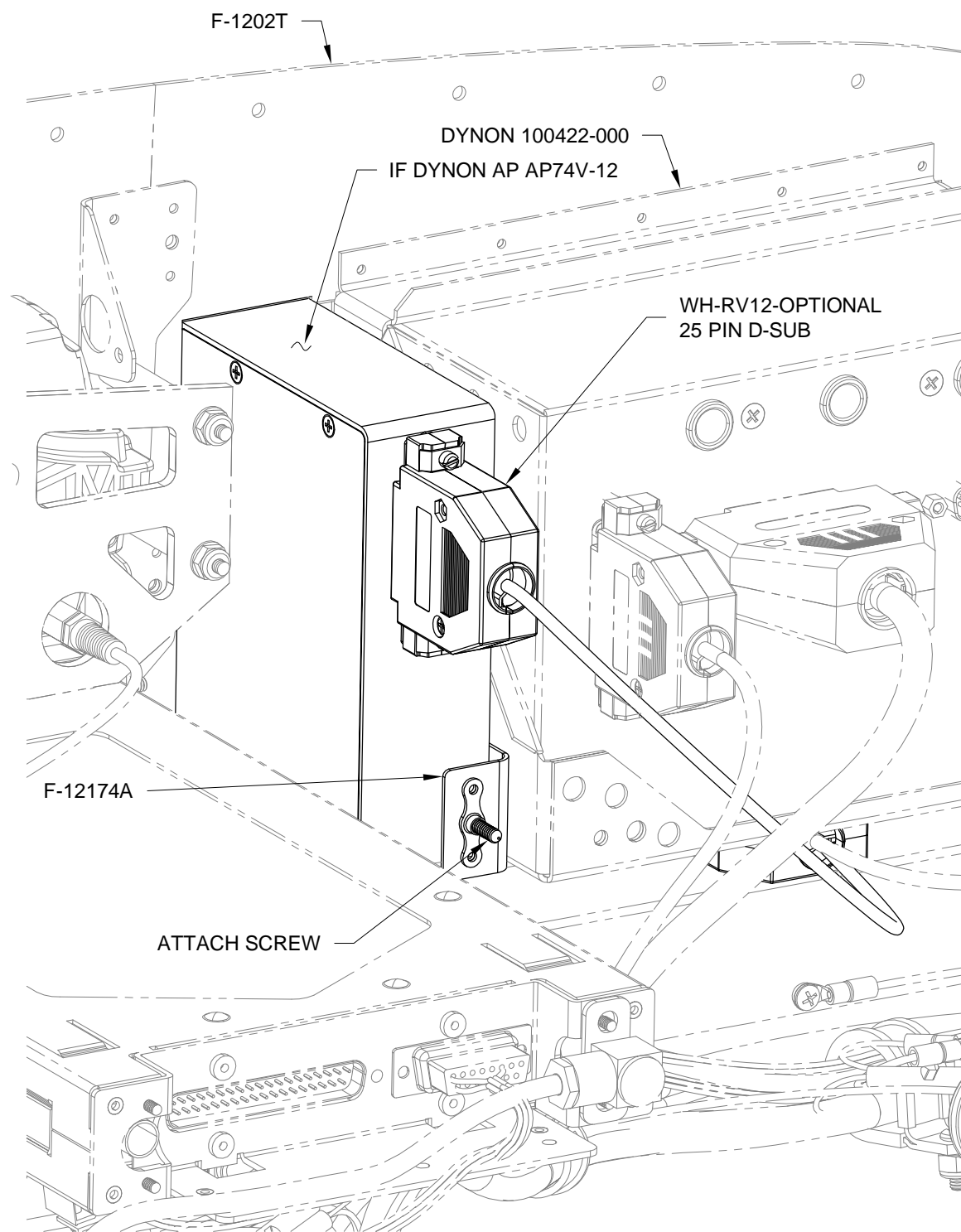
**Step 1:** Re-install the F-1202T Inst Panel Left D-180 into the aircraft. See Section 29 and Section 42 for reference.

**Step 2:** Double check that a fuse is in the autopilot position on the AV CONTROL BOARD 12. See Page 42-03, Figure 3.

**Step 3:** Slide the IF DYNON AP AP74V-12 Autopilot Module through its opening in the panel then tighten the attach screw into the nutplate on the F-12174A AP74 Mount Bracket.

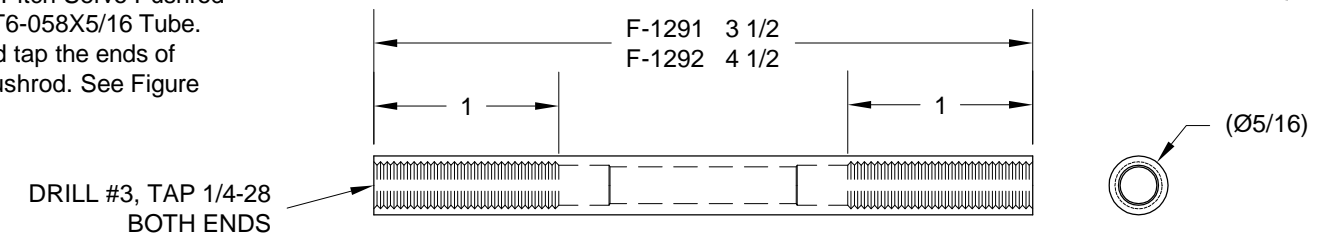
**Step 4:** Connect the 25-pin d-sub connector from the WH-RV12-OPTIONAL Optional Wiring Harness to the back of the IF DYNON AP AP74V-12 Autopilot Module.

**Step 5:** Connect the Static and Pitot Lines and WH-RV12-DYNON Dynon D-180 Harness to the back of the IF DYNON DEK 180-12 Dynon EFIS/EMS. Re-install the Dynon EFIS/EMS into the DYNON 100422-000 D-100 Series Mounting Tray.



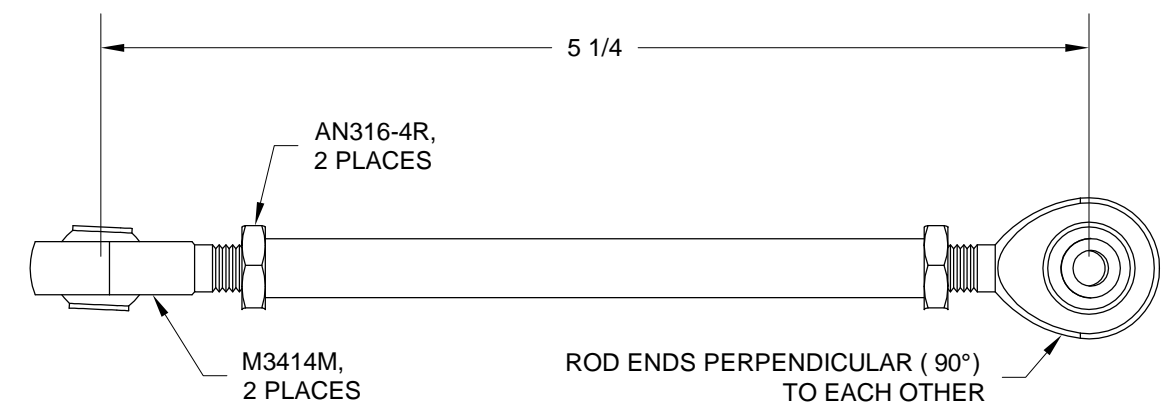
**FIGURE 1: INSTALLING THE AUTOPILOT MODULE**

**Step 6:** Cut the F-1291 Roll Servo Pushrod and the F-1292 Pitch Servo Pushrod from AT6-058X5/16 Tube. Drill and tap the ends of each pushrod. See Figure 2.



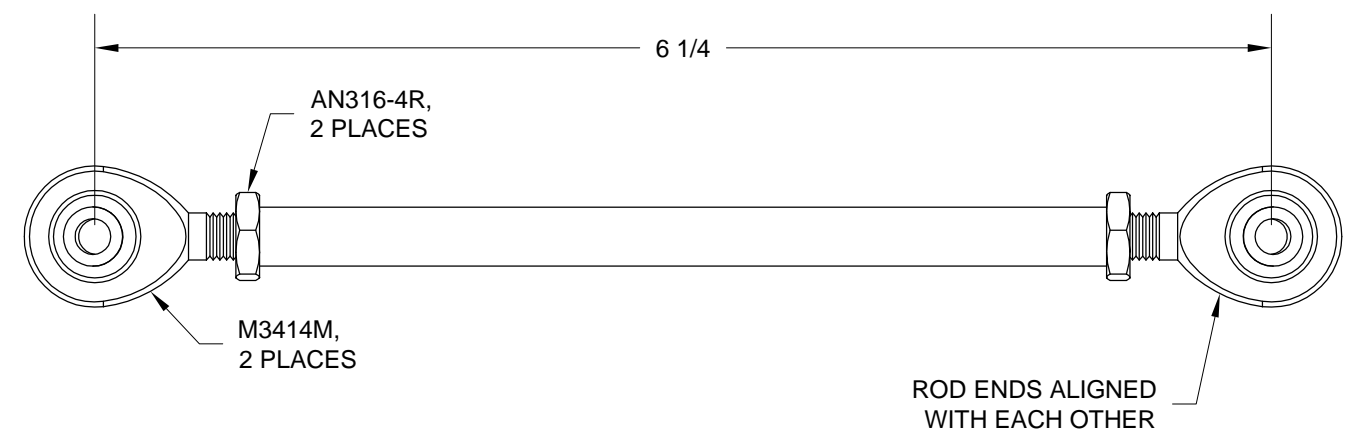
**FIGURE 2: MAKING THE PUSHROD TUBES**

**Step 7:** Assemble the F-1291 Roll Servo Pushrod and hardware as shown in Figure 3 to make the Roll Servo Pushrod Assembly.



**FIGURE 3: ROLL SERVO PUSHROD ASSEMBLY**

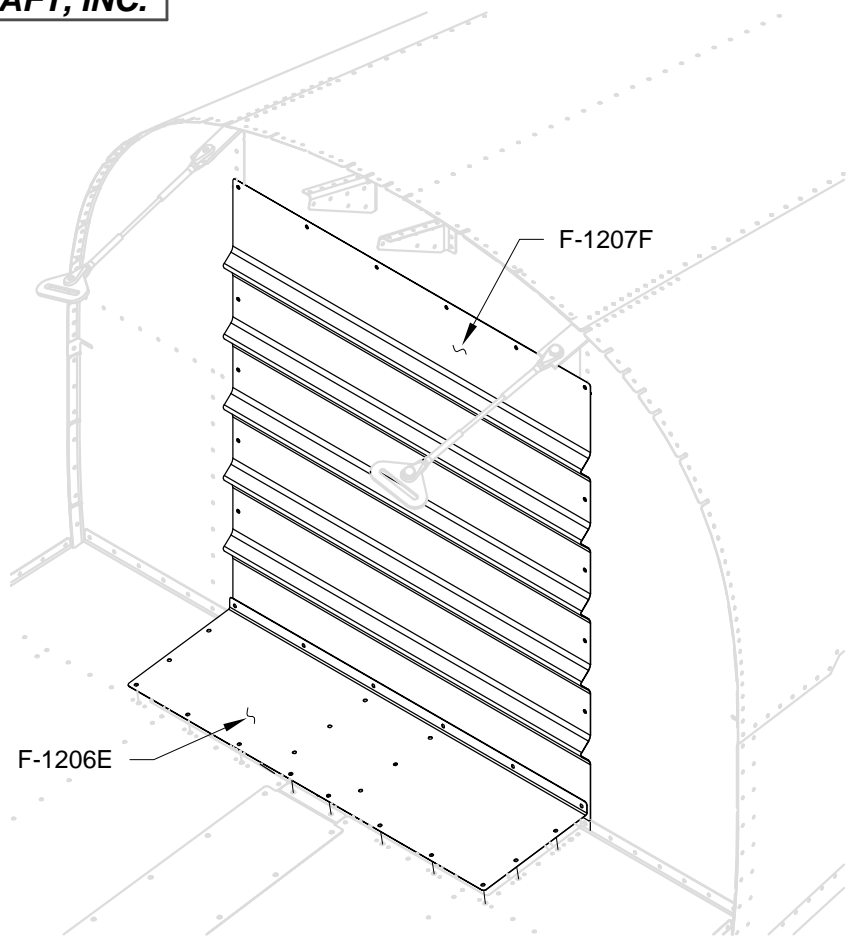
**Step 8:** Assemble the F-1292 Pitch Servo Pushrod and hardware as shown in Figure 4 to make the Pitch Servo Pushrod Assembly.



**FIGURE 4: PITCH SERVO PUSHROD ASSEMBLY**

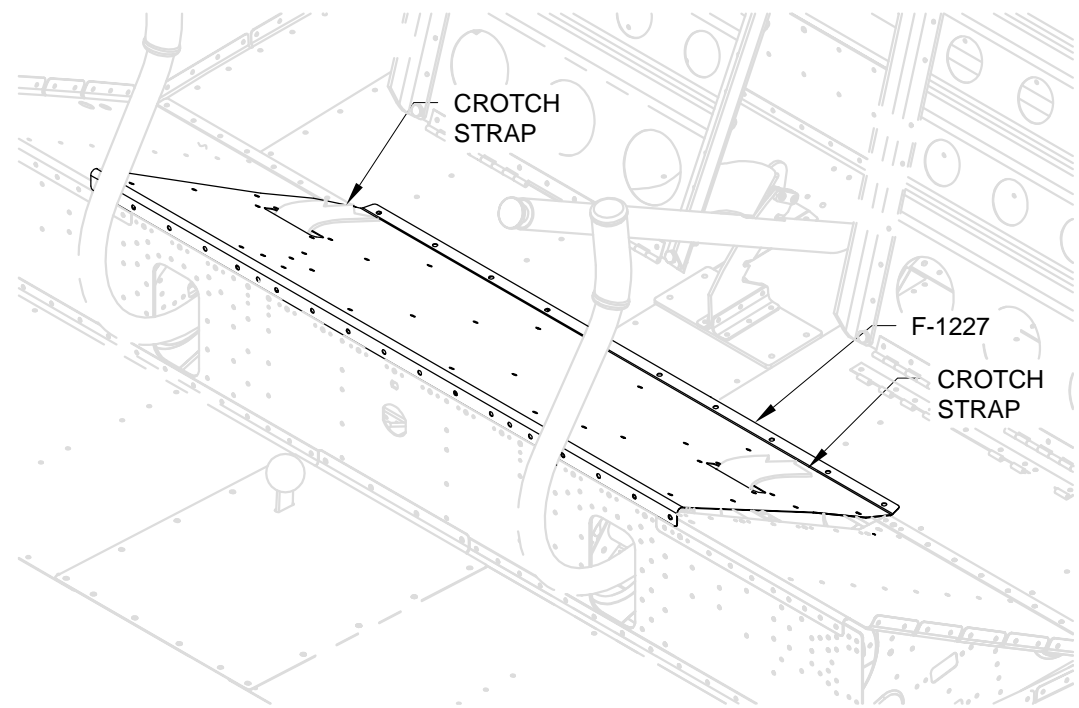


Step 1: Remove the F-1206E Baggage Cover and F-1207F Baggage Bulkhead Corrugation. See Figure 1.



**FIGURE 1: REMOVE ACCESS COVERS**

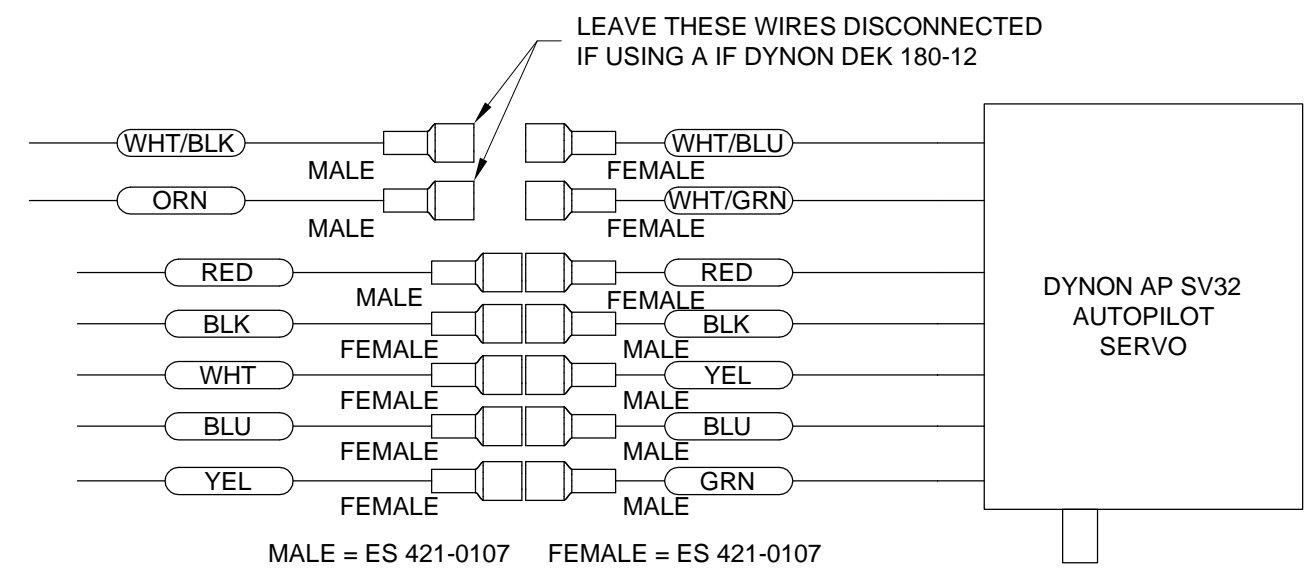
Step 2: Remove the F-1227 Seat Ramp Cover. See Figure 2.



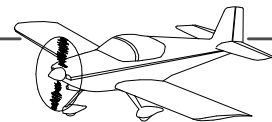
**FIGURE 2: REMOVING THE SEAT RAMP COVER**

Step 3: Strip all the wires coming from both IF DYNON AP SV32 Autopilot Servos.

Step 4: Crimp spade connectors to all of the wires on each IF DYNON AP SV32 Autopilot Servo as shown in Figure 3. Note which gender connector goes on which wire color.



**FIGURE 3: SERVO CONNECTIONS**



**Step 1:** Connect the Roll Servo Pushrod Assembly to the IF DYNON AP SV32 Autopilot Servo. See Figure 1.

**Step 2:** Connect using Page 44-04, Figure 3, the wires and corresponding spade terminals coming from the IF DYNON AP SV32 Autopilot Servo to the spade terminals on the wires in the WH-B170 Autopilot Wire.

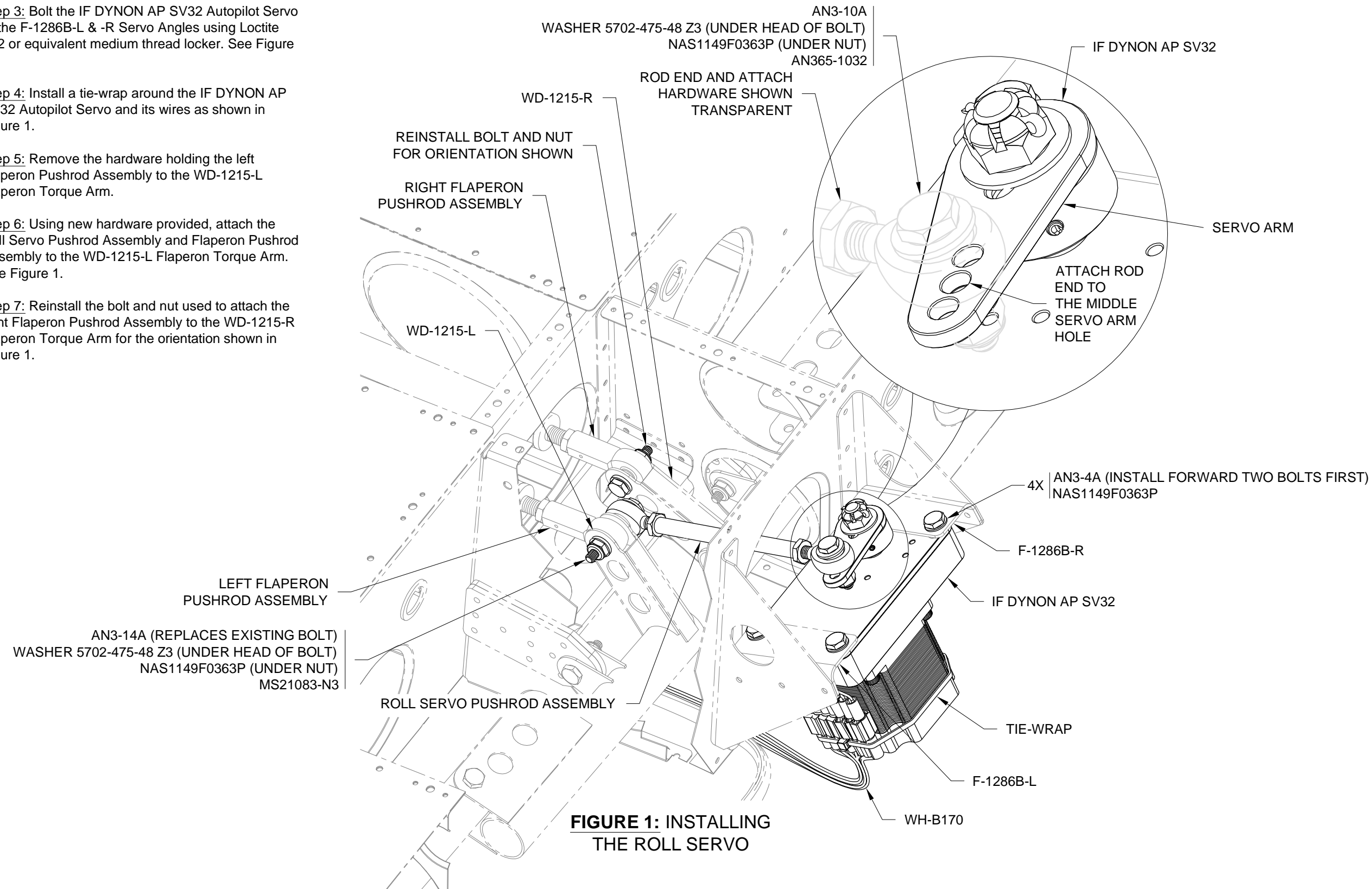
**Step 3:** Bolt the IF DYNON AP SV32 Autopilot Servo to the F-1286B-L & -R Servo Angles using Loctite 242 or equivalent medium thread locker. See Figure 1.

**Step 4:** Install a tie-wrap around the IF DYNON AP SV32 Autopilot Servo and its wires as shown in Figure 1.

**Step 5:** Remove the hardware holding the left Flaperon Pushrod Assembly to the WD-1215-L Flaperon Torque Arm.

**Step 6:** Using new hardware provided, attach the Roll Servo Pushrod Assembly and Flaperon Pushrod Assembly to the WD-1215-L Flaperon Torque Arm. See Figure 1.

**Step 7:** Reinstall the bolt and nut used to attach the right Flaperon Pushrod Assembly to the WD-1215-R Flaperon Torque Arm for the orientation shown in Figure 1.



**FIGURE 1: INSTALLING THE ROLL SERVO**





Step 1: Insert the bolt that will attach the Pitch Servo Pushrod Assembly to the arm of the IF DYNON AP SV32 Autopilot Servo.

Step 2: Attach the autopilot servo to the F-1215-R Seat Rib and F-1269 Servo Doubler using the hardware called out in Figure 1 and Loctite 242 or equivalent medium thread locker.

Step 3: Connect the Pitch Servo Pushrod Assembly to the tab on the WD-1210 Control Column and the IF DYNON AP SV32 Autopilot Servo arm. See Figure 1.

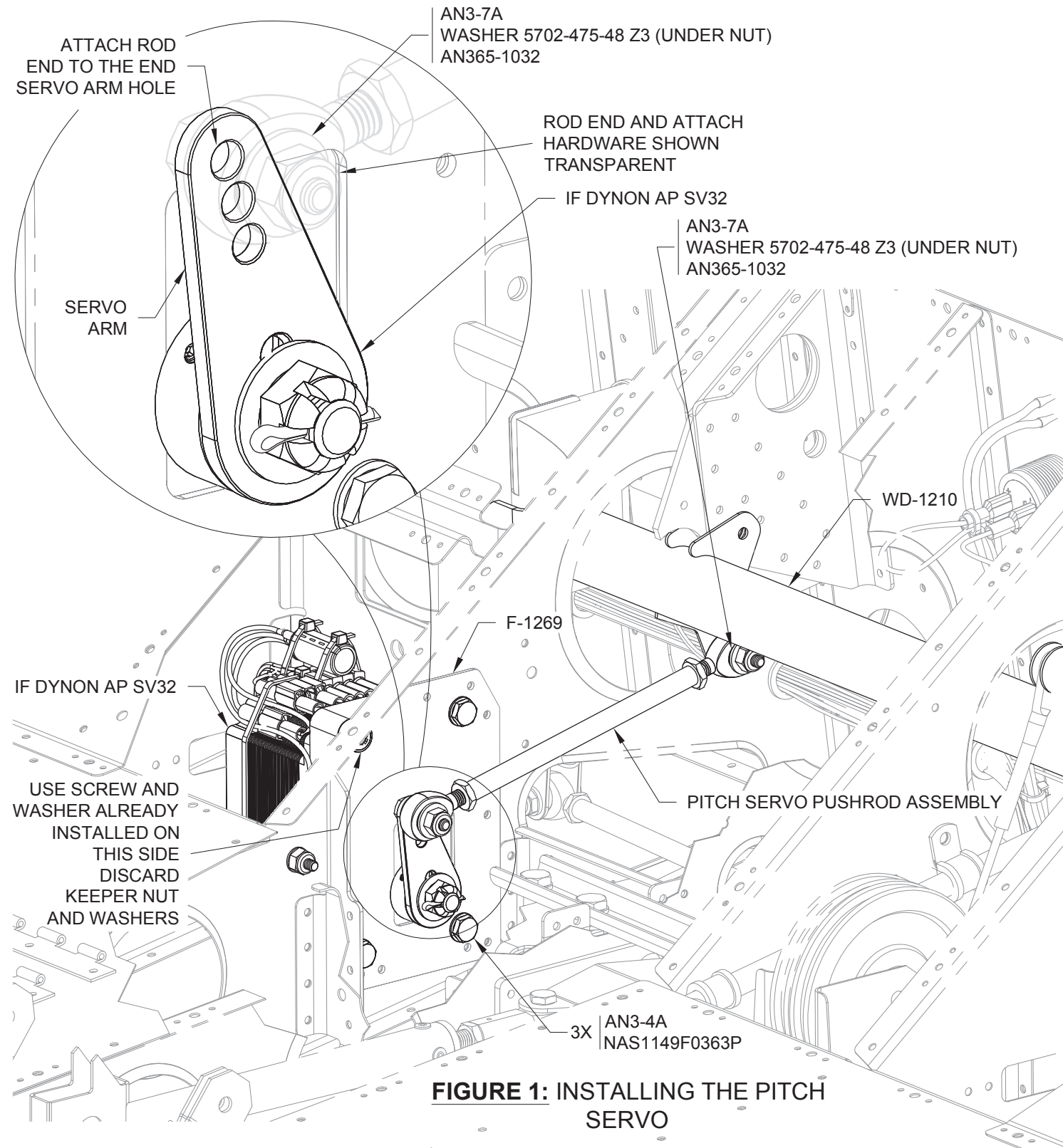


FIGURE 1: INSTALLING THE PITCH SERVO

Step 4: Connect the spade terminal on the red wire coming from the IF DYNON AP SV32 Autopilot Servo with the appropriate gender spade connector coming from the ES-00103 Noise Filter. There are two red wires crimped together in one spade connector from the WH-RV12-OPTIONAL (RED) and WH-B170 (RED) harnesses. Connect this spade connector to the remaining spade connector on the noise filter. Connect the ring terminal on the ground wire to the F-1215-R Seat Rib. See Figure 2 and Figure 3.

Step 5: Connect using Page 44-04, Figure 3, the remaining wires and corresponding spade terminals coming from the IF DYNON AP SV32 Autopilot Servo to the spade terminals on the wires of the WH-B170 Autopilot Wire.

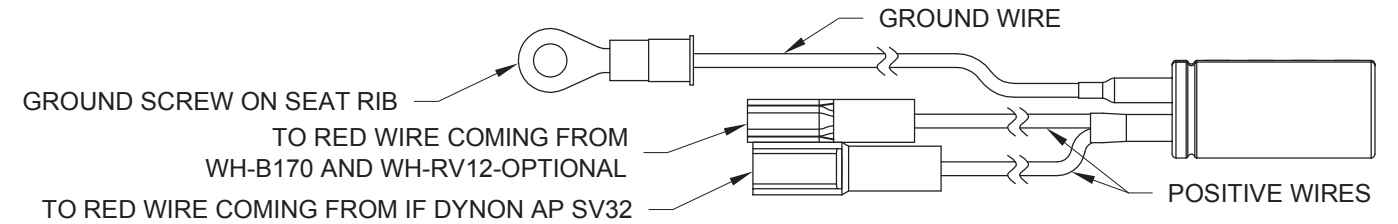


FIGURE 2: NOISE FILTER DETAIL

Step 6: Install a tie-wrap around the IF DYNON AP SV32 Autopilot Servo and its wires. Tie-wrap the ES-00103 Noise Filter to the autopilot servo wires as required to prevent wires from chafing. See Figure 1 and Figure 3.

Step 7: Check controls for full range of motion. Re-install the F-1227 Seat Ramp Cover, F-1206E Baggage Cover and F-1207F Baggage Bulkhead Corrugation.

Step 8: Follow the instructions supplied by Dynon to set up and test both the IF DYNON AP SV32 Autopilot Servos and the IF DYNON AP74V Autopilot Module.

Step 9: Adjust the corresponding volume pot on the AV CONTROL BOARD 12. See Page 45-08.

**WARNING: WHEN FINISHED INSTALLING THE AUTOPILOT SERVOS, MOVE THE CONTROL STICK THROUGHOUT ITS ENTIRE RANGE OF TRAVEL MANY TIMES (WITH FLAPS UP AND WITH FLAPS DOWN) TO CHECK FOR AN OVER-CENTER CONDITION OF THE AUTOPILOT SERVOS (A CONDITION WHERE THE SERVO ARM AND PUSHROD BECOME CLOSE TO PARALLEL AND THE CONTROL SYSTEM LOCKS).**

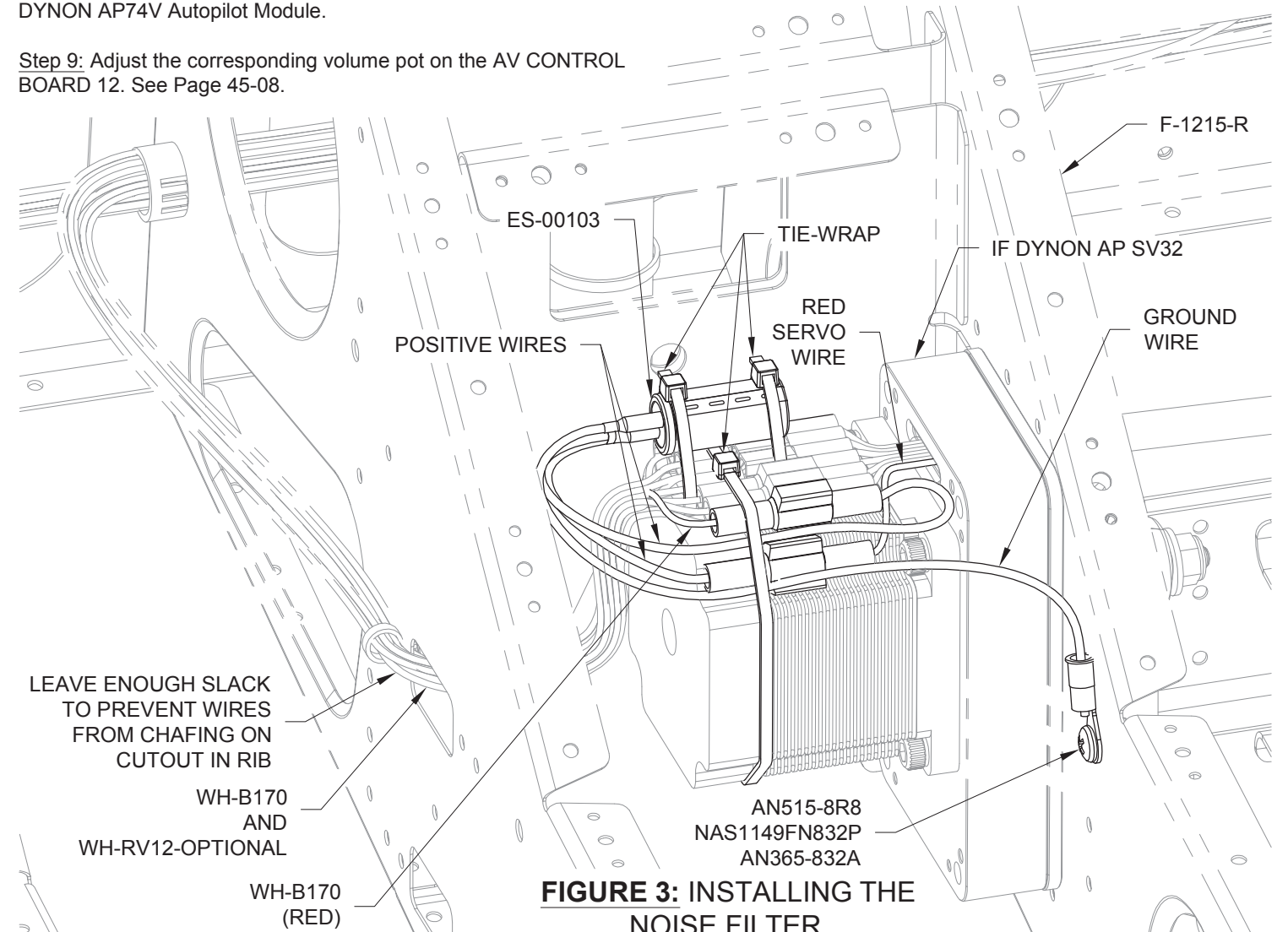


FIGURE 3: INSTALLING THE NOISE FILTER